

# Properties of Empirical Mode Decomposition

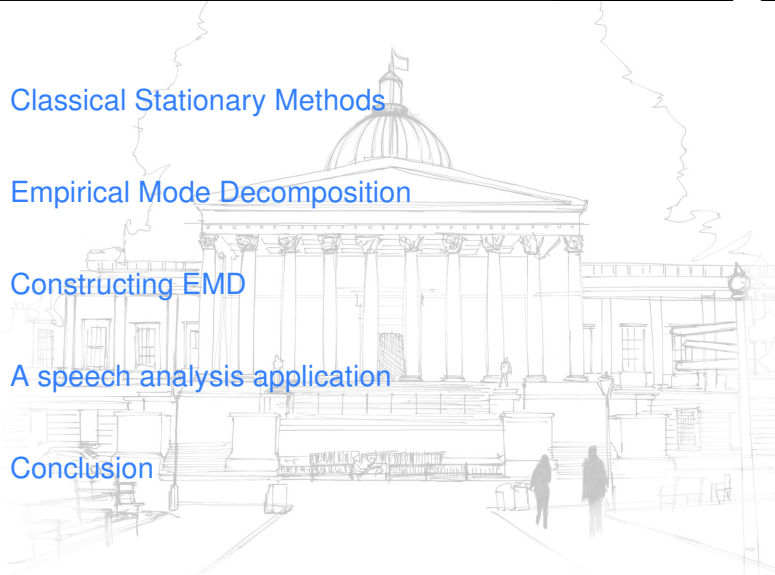
Marta Campi <sup>1</sup>, Gareth W. Peters <sup>1</sup>, Nourddine Azzaoui <sup>2</sup>  
and Tomoko Matsui <sup>3</sup>

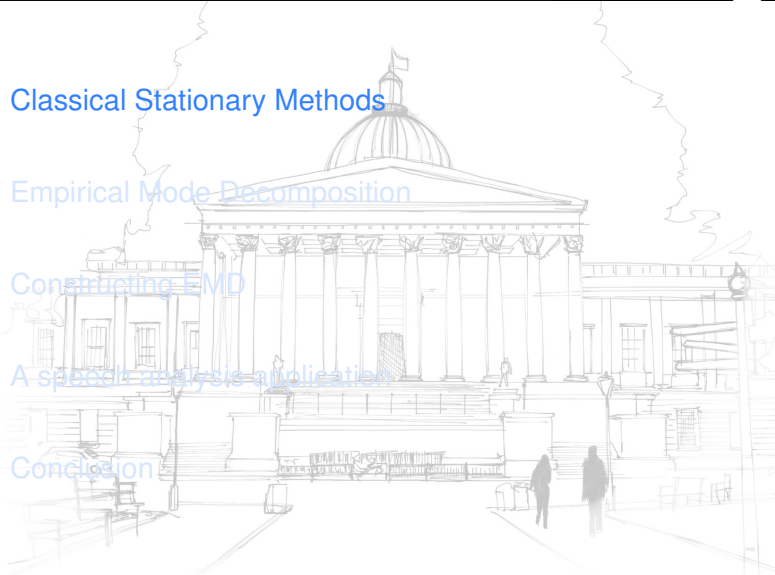
<sup>1</sup> University College London (UCL) - London, UK

<sup>2</sup> Laboratoire de Mathématiques Blaise Pascal (LBMP) - Clermont Ferrand, France

<sup>3</sup> The Institute of Statistical Mathematics (ISM) - Tokyo, Japan

February 25, 2018 - CM Statistics

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- A detailed architectural line drawing of a classical building with a prominent dome and a portico supported by columns. The drawing is rendered in a sketchy, light style. The building has a central dome with a flag on top, and a portico with several columns. There are people walking in the foreground, and some outdoor furniture like benches and a trash can are visible. The drawing is framed by a jagged, hand-drawn border.
- 1 Classical Stationary Methods
  - 2 Empirical Mode Decomposition
  - 3 Constructing EMD
  - 4 A speech analysis application
  - 5 Conclusion

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- A detailed architectural line drawing of a classical building, likely a university hall or library. It features a prominent central dome with a flag on top, a portico with several columns, and a wide set of steps leading up to the entrance. There are some figures and street furniture sketched in the foreground to provide a sense of scale and context.
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## Stochastic process and path realization

A univariate real-valued stochastic process defined as  $\{\dots X_{t_k-h}, \dots, X_{t_1}, X_{t_2}, \dots, X_{t_k+h}, \dots\} = \{X_t\}_{t=-\infty}^{\infty}$  for all  $k \in \mathbb{N}$ ,  $h \in \mathbb{R}$  is a sequence of random variables indexed by time  $t$ , with finite path realization given by

$$\{X_0 = x_0, X_1 = x_1, X_2 = x_2, \dots, X_t = x_t\} = \{x_t\}_{t=0}^T$$

The classical approach to investigate such processes is given by considering the following structure:

$$X_t \stackrel{d}{=} m_t + s_t + Y_t$$

## Strict Stationarity

A stochastic process  $\{X_t\}$  is said to be strictly stationary if:

$$(X_{t_1}, X_{t_2}, \dots, X_{t_k}) \stackrel{d}{=} (X_{t_1+h}, X_{t_2+h}, \dots, X_{t_k+h})$$

## Covariance Stationarity

A stochastic process  $\{X_t\}$  is said to be weakly stationary (or covariance stationary) if:

$$\mathbb{E}[X_t] = m \quad \text{for all } t \in T$$

$$\mathbb{E}[X_t^2] < \infty \quad \text{for all } t \in T$$

$$\text{Cov}(X_t, X_{t+h}) = \gamma(h), \quad h \in T \quad \text{such that } t+h \in T$$

## Which methods are available to decompose and analyse such stochastic processes?

### **Deterministic time**

- Splines
- Polynomial interpolation

### **Deterministic time-frequency**

- Fast Fourier Transform
- Discrete Fourier Transform

### **Stochastic time**

- ARMA model
- ARIMA model
- Etc.

### **Stochastic time-frequency**

- Fourier transform
- Wavelet Transform

## Fourier transform

$$h(\omega) = \int_{-\infty}^{+\infty} x(t) e^{-j2\pi\omega t} dt$$

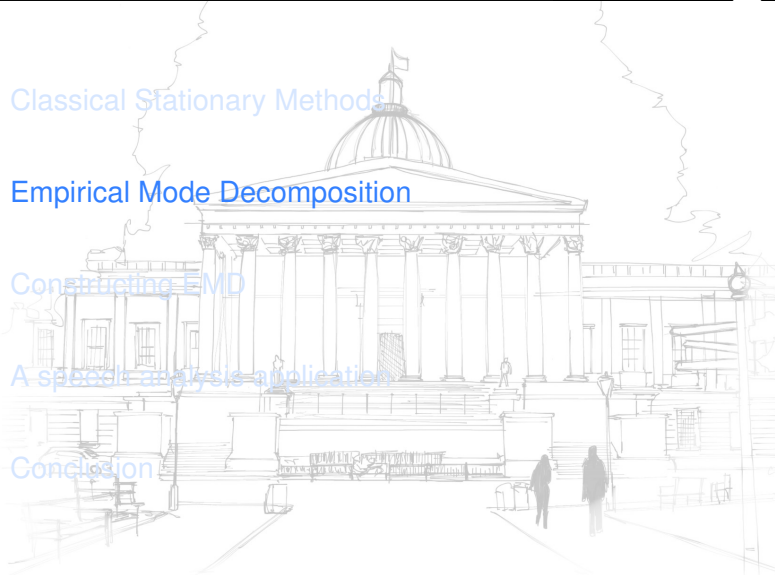
where  $h(\omega) = \mathcal{F}[x(t)]$  is such that  $h(\omega) : \mathbb{R} \rightarrow \mathbb{C}$  for any  $\omega \in \mathbb{R}$ .

## Wavelet transform

$$CWT(a, \tau; x, \psi) = \frac{1}{\sqrt{a}} \int_{-\infty}^{+\infty} x(t) \psi^* \left( \frac{t - \tau}{a} \right) dt$$

- **infinite number** of basis
- **parametric** structure
- **a-priori** basis
- **stationarity** or **linearity** of the system

What happens if some of these assumptions do not hold?

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- A detailed architectural line drawing of a classical building, likely a lecture hall or library, featuring a prominent dome and a portico with columns. The drawing is rendered in a sketchy, hand-drawn style with light lines. The building has a central dome with a flag on top, and a portico with several columns. There are people walking in the foreground, and some furniture like benches and a trash can are visible. The drawing is set against a white background with a faint, irregular outline of the building's shape.
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Given an observed time series  $\{x_t\}_{t=0}^T$ , we construct a continuous interpolation representation  $\tilde{x}(t)$ , such that  $\tilde{x}(t) \in C^1[0, T]$ .

## Oscillation of $\tilde{x}(t)$

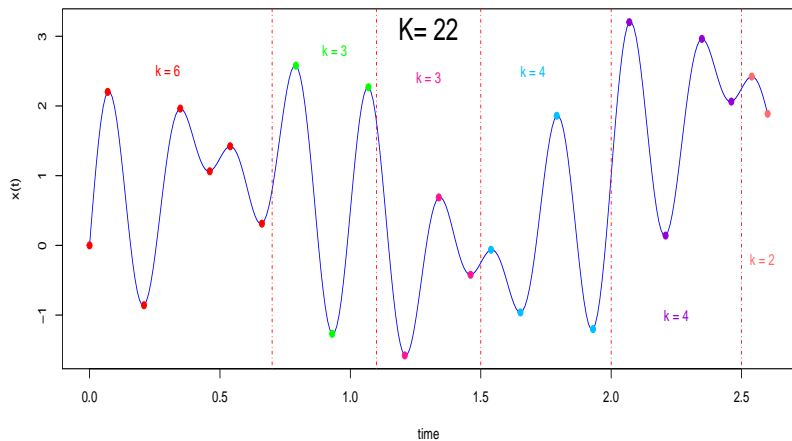
Given  $\{\tau_i\}_{i=0}^T$  such that  $0 = \tau_0 < \tau_1 < \dots < \tau_T = T$ , we define the oscillation over each interval  $\tilde{x}(\tau_i, \tau_{i+1})$  according to:

$$\text{osc}(\tilde{x}(\tau_i, \tau_{i+1})) = \left| \left\{ \frac{d}{dt} \tilde{x}(t) = 0 : t \in (\tau_i, \tau_{i+1}), \frac{d}{dt} \tilde{x}(t) \neq 0 \forall t \right\} \right| = k_i < \infty$$

with  $i = 0, \dots, T$ .

**Remark:** NO assumptions on stationarity for  $\tilde{x}(t)$ .

Let  $K = \sum_{i=0}^T k_i$  the number of turning points over  $[0, T]$ .



Can we find a finite basis decomposition admitting meaningful time and frequency domain interpretation in such a framework?

Ans: YES { N. Huang et al., 1998 }

## Empirical Mode Decomposition

$\tilde{x}(t)$  can be decomposed as:

$$\tilde{x}(t) = \sum_{k=1}^K c_k(t) + r(t) = \left( \sum_{k=1}^{K+1} c_k(t), \quad c_{k+1}(t) = r(t) \right)$$

where each  $c_k(t)$  is called **Intrinsic Mode Function** and  $r(t)$  is a final tendency or **residual**.

Define the interpolations of maxima and minima of  $\tilde{x}(t)$  as **upper envelope**  $M(t)$  and **lower envelope**  $m(t)$  respectively and the **mean envelope** as  $d(t) = \frac{M(t)+m(t)}{2}$ .

The IMF basis  $\{c_k(t)\}_{k=1}^K$  are designed to satisfy the following two conditions:

- *Local symmetry* At any point, the mean value of the envelope defined by the local maxima and the envelope defined by the local minima is zero.
- *Oscillations* The number of extrema and the number of zero-crossings must either equal or differ at most by one.

$$M(t) > \tilde{x}(t) \quad \text{and} \quad \tilde{x}(t) < m(t) \quad \forall t \quad \text{except} \quad \tau_0, \tau_1, \dots, \tau_T$$

The residual  $r(t)$  is designed to satisfy the following condition:

The residual is a curve with at most one extremum.

$$\text{osc}(r(t)) \in \{0, 1\}$$

$$r'(t) \geq 0 \quad \text{or} \quad r'(t) < 0 \quad \text{over} \quad [0, T]$$

## Instantaneous frequency

$$f_k(t) = \frac{1}{2\pi} \frac{d\theta_k(t)}{dt}$$

An analytical signal is defined as  $z_k(t) = c_k(t) + jy_k(t)$  or  $z_k(t) = a_k(t)e^{j\theta_k(t)}$  where

- $a_k(t)$  is the **amplitude** of  $z(t)$
- $\theta_k(t) = \arctan \frac{y_k(t)}{c_k(t)}$  is the **instantaneous phase**.

Recall:  $\tilde{x}(t) = \sum_{k=1}^K c_k(t) + r(t)$

## Hilbert transform (Cauchy Principal Value Integral)

$$y_k(t) = -\frac{1}{\pi} \lim_{\epsilon \rightarrow \infty} \int_{-\epsilon}^{+\epsilon} \frac{c_k(t + \tau) - c_k(t - \tau)}{t} d\tau$$

This concept makes sense when the signal  $z_k(t)$  is almost circular within the complex domain.

The EMD provides such property, therefore after the EMD and the Hilbert transform each IMF  $c_k(t)$  and  $\tilde{x}(t)$  are expressed respectively as:

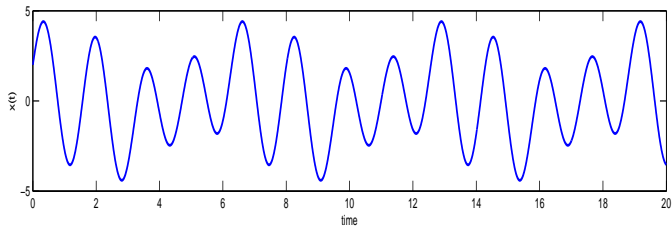
$$c_k(t) = \text{Re} \left\{ a_k(t) \exp \left( j \int 2\pi f_k(t) dt \right) \right\}$$

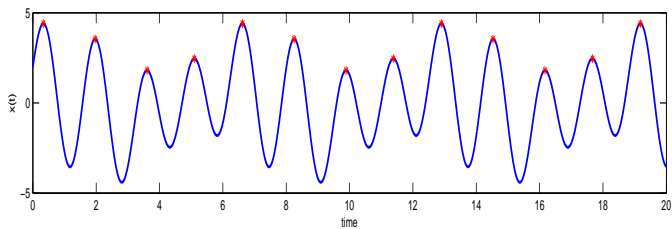
$$\tilde{x}(t) = \text{Re} \left\{ \sum_{k=1}^{K+1} a_k(t) \exp \left( j \int 2\pi f_k(t) dt \right) \right\}$$

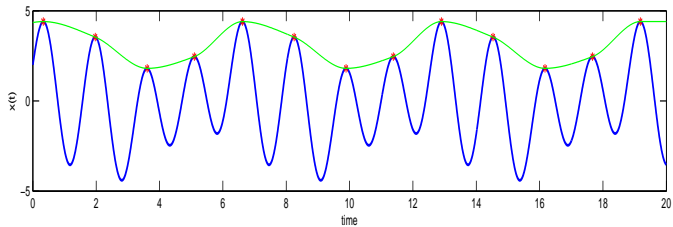
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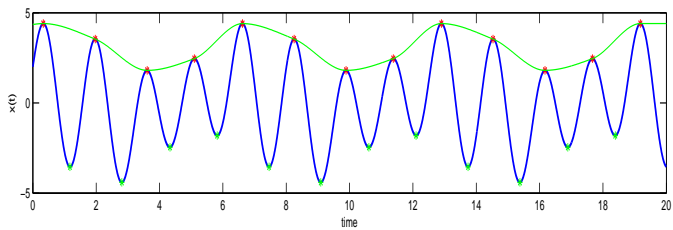
- 1 **Step 1** Find local extrema of  $\tilde{x}(t)$
- 2 **Step 2** Compute the upper envelope  $M(t)$  and the lower envelope  $m(t)$  by employing spline interpolations (cubic, akima, b-spline, etc.)
- 3 **Step 3** Update the signal  $\tilde{x}(t) \leftarrow \tilde{x}(t) - \frac{M(t)+m(t)}{2}$
- 4 **Step 4** Repeat 1, 2 and 3 until achieving an IMF  $c_k(t)$
- 5 **Step 5** Subtract the obtained IMF from the signal  $\tilde{x}(t) \leftarrow \tilde{x}(t) - c_k(t)$
- 6 **Step 6** Repeat 1-5 until achieving a tendency

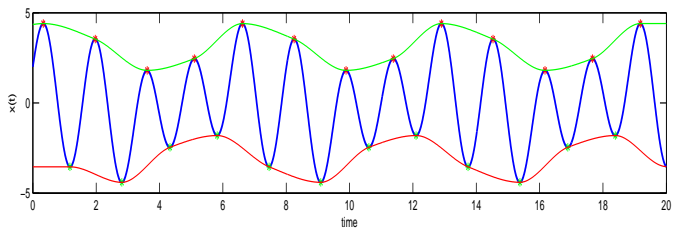


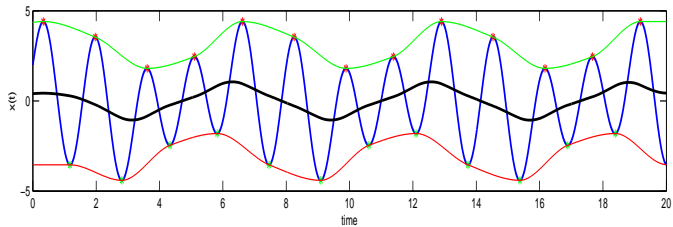


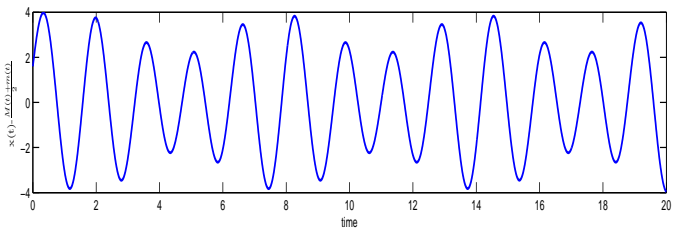
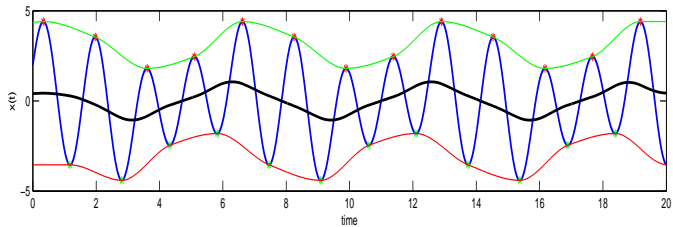


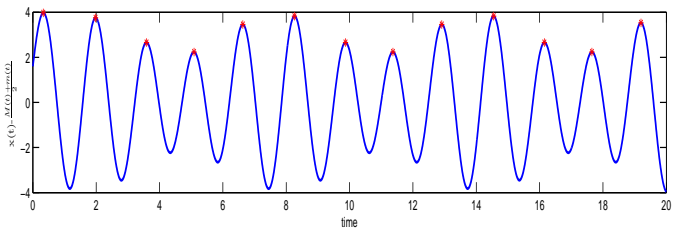
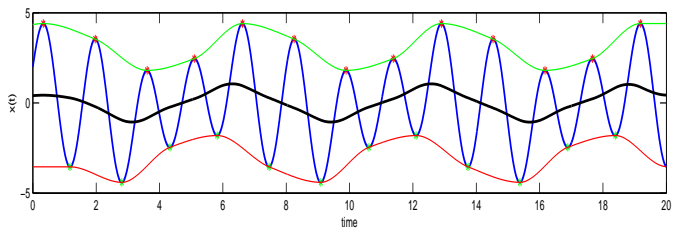




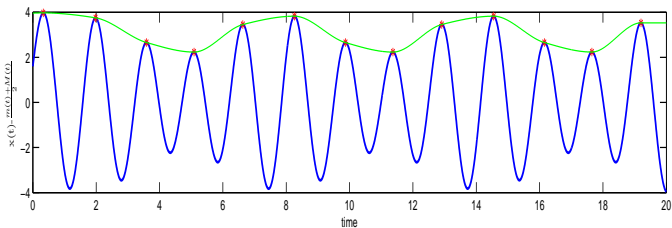
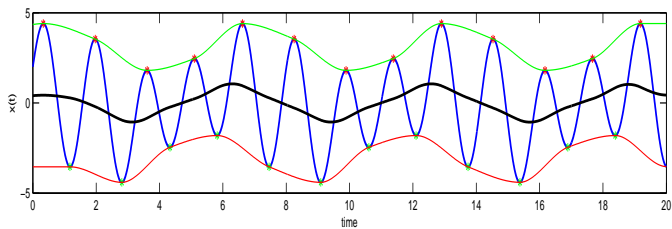


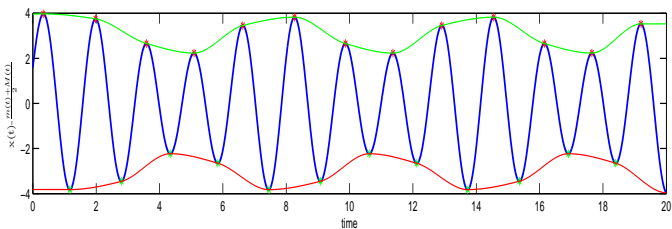
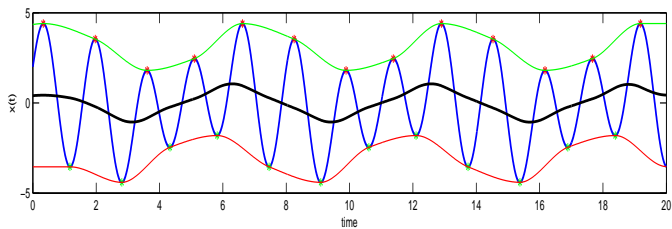


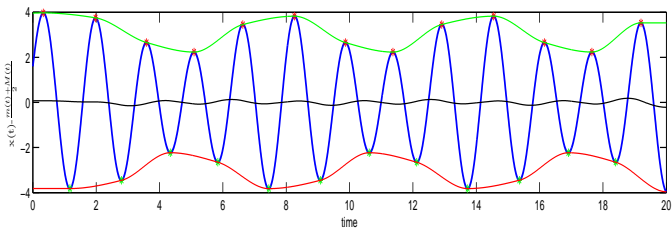
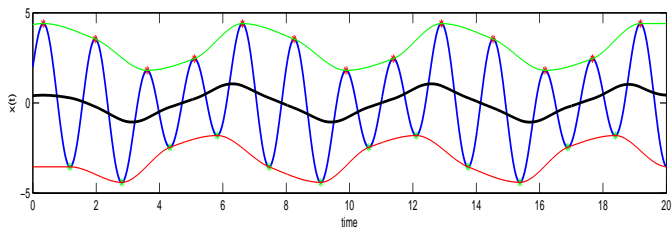


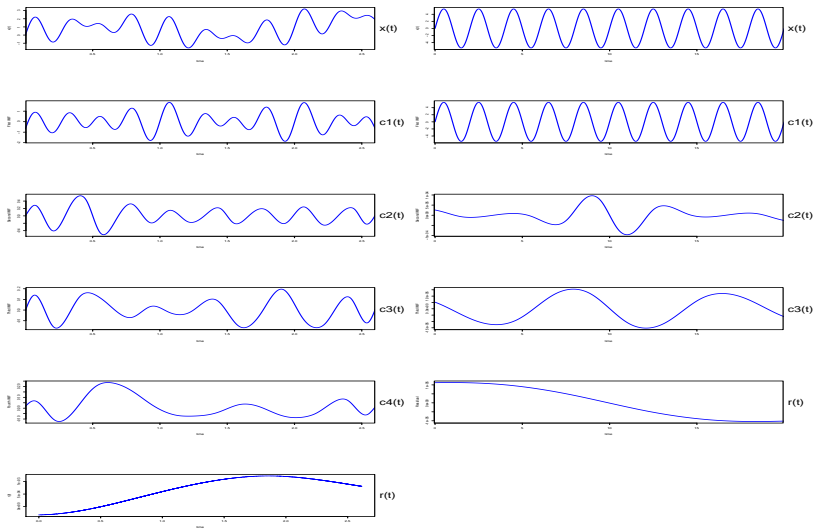


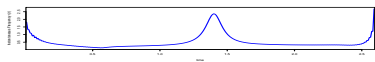
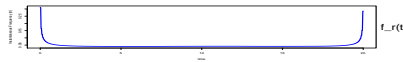
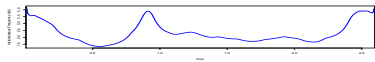
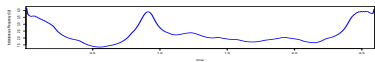
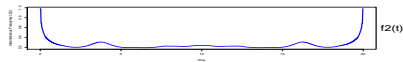
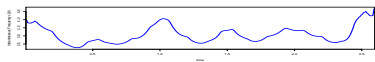
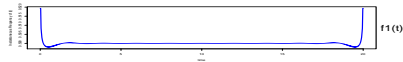
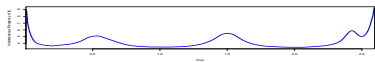






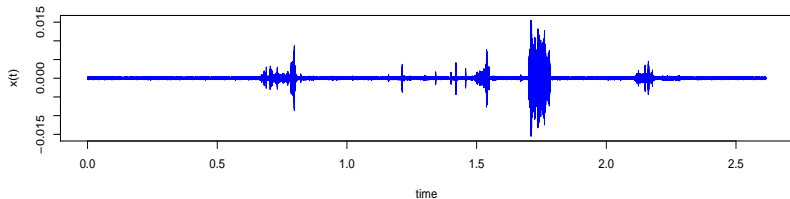




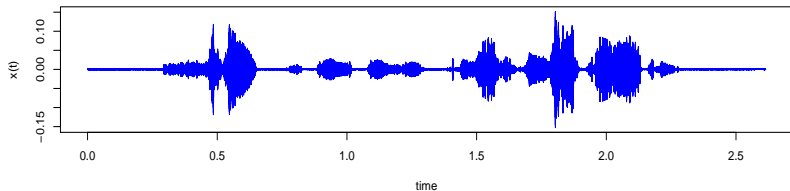


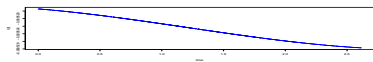
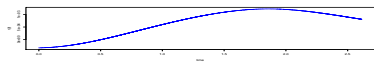
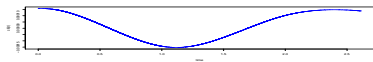
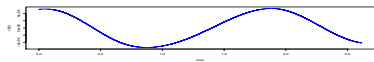
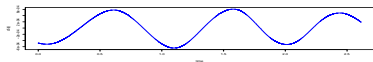
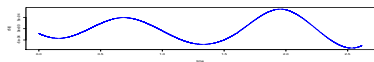
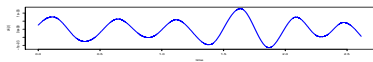
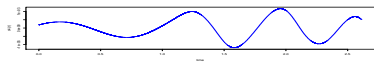
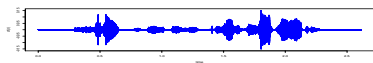
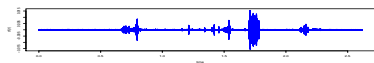
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Human voice signal



Synthesized voice signal







Classifier features:

- **Intrinsic Mode Functions:**  $c_1(t), c_2(t), \dots, r(t)$ .
- **Instantaneous frequencies:**  $f_1(t), f_2(t), \dots, f_r(t)$ .
- **Coefficients splines** used to represent the IMFs.
- **Classical Statistics.**

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- Exploiting an a posteriori time-frequency decomposition for **non-stationary and non-linear** systems with minimal restrictions.
- A close form of the Huang-Hilbert transform leading to a **close form of the instantaneous frequency**.
- Study of the **constructing algorithm** and its performances according to its heuristic rules (future research aimed to improve it).
- Using such a decomposition for features extraction and classification.
- A speech analysis application.